Computer Science 294 Lecture 4 Notes

Daniel Raban

January 26, 2023

1 Properties of Effect and Influence

1.1 Recap: voting rules, effect, and influence

Last time, we discussed thinking of a boolean function $f : \{\pm 1\}^n \to \{\pm 1\}$ as a voting rule. We had a number of examples, including the Majority, And, Or, Dictator, and Tribes functions. We also defined the influence

$$Inf_{i}(f) = \mathbb{P}_{X \sim \{\pm 1\}^{n}}(f(X) \neq f(X^{\oplus i})), \qquad x^{\oplus i} = x_{1}, \dots, x_{i-1}, -x_{i}, x_{i+1}, \dots, x_{n})$$

and the effect

$$\mathrm{Eff}_i(f) = \mathbb{P}_{X \sim \{\pm 1\}^n}(f(X) = 1 \mid X_i = 1) - \mathbb{P}_{X \sim \{\pm 1\}^n}(f(X) = 1 \mid X_i = -1) = \widehat{f}(\{i\}).$$

To derive a Fourier representation for the influence, we introduced the derivative

$$D_i f(x) = \frac{f(x^{(i\mapsto 1)}) - f(x^{(i\mapsto -1)})}{2}.$$

If f is a boolean function, then we saw that

$$D_i f(x) = \begin{cases} \pm 1 & \text{if } i \text{ is pivotal} \\ 0 & \text{otherwise.} \end{cases}$$

1.2 Fourier representations of effect and influence

From the definition,

$$\operatorname{Inf}_{i}(f) = \mathbb{E}[(D_{i}f(X))^{2}].$$

Recall that the fundamental theorem of boolean functions gives

$$f(x) = \sum_{S \subseteq [n]} \widehat{f}(S) \chi_S(x), \qquad \chi_S = \prod_{i \in S} x_i.$$

Proposition 1.1. $D_i f : \{\pm 1\}^n \to \mathbb{R}$ can be expressed as

$$D_i f(x) \sum_{S \subseteq [n]: S \ni i} \widehat{f}(S) \prod_{j \in S \setminus \{i\}} x_j$$

Example 1.1. If $f(x) = \frac{1}{2}x - 1x_2 + \frac{1}{2}x_3x_4$, then $D_1f(x) = \frac{1}{2}x_2$.

Proof. D_i is a linear operator:

$$D_i(f+g) = D_i f + D_i g, \qquad D_i(\alpha f) = \alpha D_i f f$$

We can write f as a linear combination of characters, so it suffices to see what D_i does to a single character. In particular, we want to show

$$D_i \chi_S = \begin{cases} \chi_{S \setminus \{i\}} & i \in S \\ 0 & i \notin S \end{cases}$$

When $i \in S$,

$$D_{i} \prod_{j \in S} x_{i} = \frac{\prod_{j \in S \setminus \{i\}} x_{j} \cdot 1 - \prod_{j \in S \setminus \{i\}} x_{j} \cdot (-1)}{2}$$
$$= \prod_{j \in S \setminus \{i\}} x_{j}.$$

The definition $\operatorname{Inf}_i(f) = \mathbb{E}[(D_i f(X))^2]$ makes sense for any $f : \{\pm 1\}^n \to \mathbb{R}$, not just boolean functions.

Lemma 1.1.

$$\operatorname{Inf}_{i}(f) = \sum_{S \ni i} \widehat{f}(S)^{2}.$$

Proof.

$$\operatorname{Inf}_i(f) = \langle D_i f, D_i f \rangle$$

Using Parseval's identity,

$$=\sum_{S\subseteq [n]}\widehat{D_if}(S)^2$$

The previous proposition tells us that if $i \notin S$, $\widehat{D_i f}(S) = \widehat{f}(S \cup \{i\})$. If S contains i, then $\widehat{D_i f}(S) = 0$.

$$=\sum_{T\ni i}\widehat{f}(T)^2.$$

Lemma 1.2.

$$\operatorname{Eff}_i(f) = \mathbb{E}[D_i f(X)].$$

Proof.

$$\mathbb{E}_{X \sim \{\pm 1\}^n} [D_i f(X)] = \langle D_i f(X), 1 \rangle$$

= $\widehat{D_i f}(\emptyset)$
= $\widehat{f}(\{i\})$
= $\mathrm{Eff}_i(f).$

Corollary 1.1. For any $f : \{\pm 1\}^n \to \{\pm 1\}$ and any coordinate *i*,

$$\operatorname{Eff}_i(f) \le \operatorname{Inf}_i(f)$$

Proof.

Since $D_i f$

$$\operatorname{Eff}_{i}(f) = \mathbb{E}[D_{i}f(X)]$$

equals -1, 0, or +1,
$$= \mathbb{E}[(D_{i}f(X))^{2}]$$
$$= \operatorname{Inf}_{i}(f).$$

Remark 1.1. We can think of the effect as how likely person i can change the result if they move first, whereas the influence is how likely person i can change the result if they move last. So in general, person i has more power if they move last.

Remark 1.2. We have equality if and only if f is monotone in the *i*-th direction.

1.3 Total influences and total effects

Definition 1.1. The **total influence** of a function $f : \{\pm 1\}^n \to \mathbb{R}$ is

$$\mathbb{I}(f) = \sum_{i \in [n]} \operatorname{Inf}_i(f).$$

Definition 1.2. The total effect of a function $f : \{\pm 1\}^n \to \mathbb{R}$ is

$$\operatorname{Eff}(f) = \sum_{i \in [n]} \operatorname{Eff}_i(f).$$

Example 1.2. Since the Majority function is symmetric,

$$\mathbb{I}(\mathrm{MAJ}_n) = n \operatorname{Inf}_1(\mathrm{MAJ}_n) \approx n \cdot \sqrt{\frac{2}{\pi}} \frac{1}{\sqrt{n}} = \Theta(\sqrt{n}).$$

Example 1.3. The Parity function is symmetric, so

$$\mathbb{I}(\operatorname{Parity}_n) = n \operatorname{Inf}_1(\operatorname{Parity}) = n.$$

Example 1.4.

$$\mathbb{I}(\chi_i) = \sum_{j \in [n]} \operatorname{Inf}_j(\chi_i) = \operatorname{Inf}_i(\chi_i) = 1.$$

Example 1.5. For the Tribes function, we are taking the Or of s Ands of w voters each. To find the influence of voter 1, observe that voter 1's vote is pivotal only when all other tribes vote False, but all other members of x_1 's tribe vote True.

$$\mathbb{P}_{X_2,\dots,X_n}(X_1 \text{ is pivotal for Tribes}) = \mathbb{P}(\text{all other members of 1's Tribes vote True}) \\ \cdot \mathbb{P}(\text{all other Tribes vote False})$$

$$= \left(\frac{1}{2}\right)^{w-1} \cdot \left(1 - \frac{1}{2^w}\right)^{s-1}$$

Taking $s \approx \ln 2 \cdot 2^w$,

$$\approx \frac{1}{2^w} \\ = \Theta\left(\frac{\log n}{n}\right).$$

So the total influence of Tribes is

$$\mathbb{I}(\operatorname{Tribes}_n) = \Theta(\log n).$$

You may wonder if a voting rule which is relatively stable can give all voters low influence.

Theorem 1.1 (KKL). If $f : \{\pm 1\}^n \to \{\pm 1\}$ and $\operatorname{Var}(f) = \Omega(1)$, then there exists a coordinate *i* with influence $\operatorname{Inf}_i \ge \Omega(\frac{\log n}{n})$.

To prove this, we will need some more machinery.

1.4 Sensitivity and interpretations of total influence

Definition 1.3. The sensitivity of f at x is

 $\operatorname{Sens}_f(x) = \#$ of pivotal coordinates on x.

Lemma 1.3.

 $\mathbb{I}(f) = \mathbb{E}_{X \sim \{\pm 1\}^n}[\operatorname{Sens}_f(X)].$

So the total influence equals the average sensitivity.

Proof.

$$\begin{split} \mathbb{I}(f) &= \sum_{i \in [n]} \operatorname{Inf}_{i}(f) \\ &= \sum_{i=1}^{n} \mathbb{P}_{X \sim \{\pm 1\}^{n}}(f(X) \neq f(X^{\oplus i})) \\ &= \sum_{i=1}^{n} \mathbb{E}_{X \sim \{\pm 1\}^{n}}[\mathbb{1}_{\{f(X) \neq f(X^{\oplus i})\}}] \\ &= \mathbb{E}_{X}\left[\sum_{i=1}^{n} \mathbb{1}_{\{f(X) \neq f(X^{\oplus i})\}}\right] \\ &= \mathbb{E}_{X}[\operatorname{Sens}_{f}(X)]. \end{split}$$

Remark 1.3. Recall that

$$Inf_i(f) = \frac{\# \text{ of sensitive edges in direction } i}{2^{n-1}},$$

 \mathbf{SO}

$$\mathbb{I}(f) = \frac{\# \text{ of sensitive edges}}{2^{n-1}}$$

Here is a third interpretation of total influence.

Lemma 1.4.

$$\mathbb{I}(f) = \sum_{S \subseteq [n]} \widehat{f}(S)^2 \cdot |S|.$$

Proof.

$$\mathbb{I}(f) = \sum_{i=1}^{n} \operatorname{Inf}_{i}(f)$$
$$= \sum_{i=1}^{n} \sum_{S \ni i} \widehat{f}(S)^{2}$$

Each coordinate is counted each time it shows up in a set.

$$=\sum_{S\subseteq[n]}\widehat{f}(S)^2\cdot|S|.$$

For any boolean function $f: \{\pm 1\}^n \to \{\pm 1\}$, we know

$$f(x) = \sum_{S \subseteq [n]} \widehat{f}(S) \cdot \prod_{i \in S} x_i, \qquad \sum_{S \subseteq [n]} \widehat{f}(S)^2 = 1.$$

Define the distribution \mathscr{S}_f over subsets $S \subseteq [n]$, where S is sampled with probability $\widehat{f}(S)^2$.

Example 1.6. Recall MAJ₃ $(x_1, x_2, x_3) = \frac{1}{2}x_1 + \frac{1}{2}x_2 + \frac{1}{2}x_3 - \frac{1}{2}x_1x_2x_3$. This distribution would pick {1}, {2}, {3}, {1, 2, 3} each with probability 1/4.

This gives the interpretation

$$\mathbb{I}(f) = \mathbb{E}_{S \sim \mathscr{S}_f}[|S|] = \sum_{S \subseteq [n]} \widehat{f}(S)^2 \cdot |S|.$$

Remark 1.4. The distribution \mathscr{S}_f with maximal entropy is the uniform distribution over all subsets. This corresponds to

$$f(x) = x_1 x_2 \oplus x_3 x_4 \oplus \cdots \oplus x_{n-1} x_n,$$

where we are thinking of the x_i as elements of \mathbb{F}_2 . Check that $\widehat{f}(S) = \pm 2^{-n/2}$.

By Markov's inequality,

$$\mathbb{P}_{S \sim \mathscr{S}_f}(|S| \ge \underbrace{\mathbb{E}[|S|]}_{\mathbb{I}(f)} \cdot c) \le \frac{1}{c}$$

Which boolean function maximizes $\mathbb{I}(f)$? This is the partial function $\prod_i x_i$. Which boolean function maximizes $\mathrm{Eff}(f)$? It turns out this is the Majority function.

Proposition 1.2. Let n be odd. Among all boolean functions on n variables, MAJ_n is the unique maximizer of Eff(f).

Proof. Let $f: \{\pm 1\}^n \to \{\pm 1\}$ be any boolean function on n variables.

$$\operatorname{Eff}(f) = \sum_{i=1}^{n} \widehat{f}(\{i\})$$
$$= \sum_{i=1}^{n} \mathbb{E}_{X}[f(X)X_{i}]$$
$$= \mathbb{E}_{X}\left[f(X)\sum_{i=1}^{n} X_{i}\right]$$

To maximize this, we need to take $f(x) = \operatorname{sgn}(\sum_{i=1}^{n} x_i)$, which is the Majority function. \Box

Next time, we will given an interpretation of influence in terms of an isoperimetric inequality on the hypercube, and we will prove Arrow's theorem.